

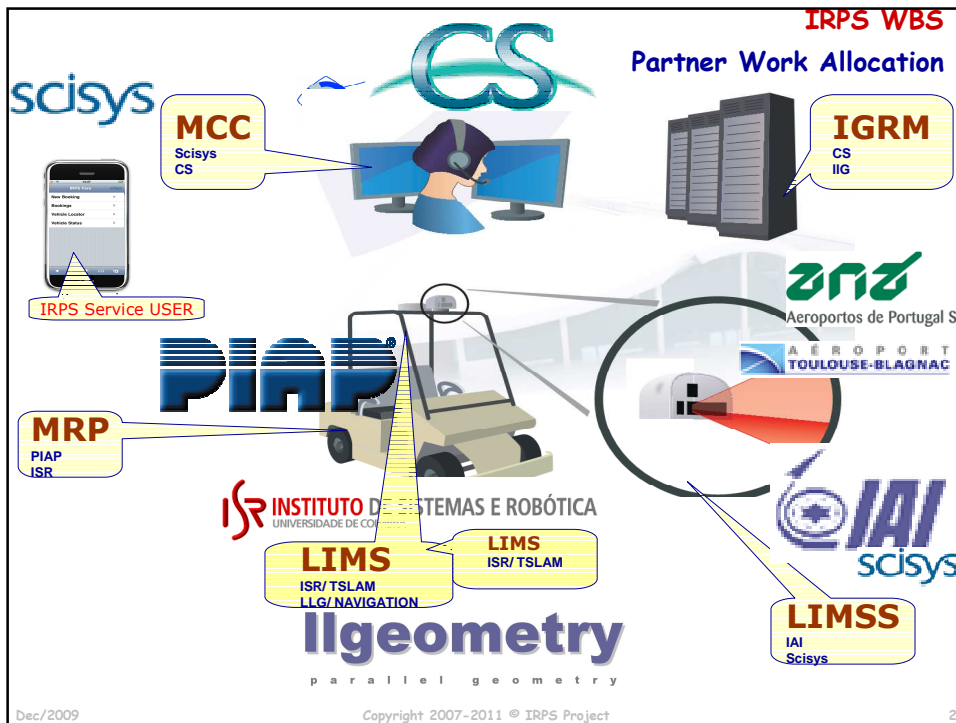
APRESENTAÇÃO PÚBLICA IRPS PUBLIC PRESENTATION INTELLIGENT ROBOT PORTER SYSTEM

Front Page

Public Presentation		
Time	Duration	Agenda items
9:30	0:30	Register - coffee
10:00	0:15	Opening
10:15	0:45	Project overview and main achievements
11:00	1:30	Demo - IRPS
12:30	0:15	Questions/Debate
12:45	0:15	Closing
13:00		Lunch

Main Stakeholders Presentation		
Time	Duration	Agenda items
14:30	1:30	Technology - Presentation
16:00	1:00	LIMS - Presentation
17:00	0:15	Closing

Faro 17/12/09



IRPS Achievements

- **Cooperative Project**
 - Technology Innovation brought from lab to Operational application
 - IRPS Service Demonstration (IRPS Simulators+ Live demos)
 - IRPS/ LIMS showcase
- **Technology Integration & Showcase**
 - Mobile Robotic Platform : MRP development & Integration (PIAP, ISR)
 - LIDAR Measurement System Sensor :LIMSS development & Integration. (IAI, Scisys)
 - LIDAR Measurement System development & Integration (LLG,ISR,CS)
 - Mission Control Center MCC development & Integration (Scisys, CS)
 - IRPS Global Reference Model IGRM development & Integration (CS, LLG)

Dec/2009

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091217_IFE Public Presentation

- We have demonstrated an IRPS system to support 3D sensing and localization based on innovative technologies.
- **This work was performed as a Collaborative Project between Technology providers, Service providers and end-users**
 - Technology Innovation was brought from labs to an application demonstrator (prototype)
 - IRPS Service Demonstration produced (IRPS Simulator+ Live demos) for dissemination.
- **Research Results were integrated and demonstrated as a prototype, not everything could be fully worked out, partners are ready to exploit the results towards industrial applications. This event is not an end, but rather marks the start of new endeavours.**
- **For any additional information,**
 - See our website www.irps-project.net
 - Contact maurice.heizt@c-s.fr

